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# **CANard Documentation**

***Release 0.1***

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CANard is a library for dealing with Controller Area Network (CAN) data from Python.



# CHAPTER 1

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## Submodules

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**1.1 canard.bus module**

**1.2 canard.can module**

**1.3 canard.log module**





# CHAPTER 2

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## Subpackages

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### 2.1 canard.hw package

#### 2.1.1 Submodules

[canard.hw.cantact module](#)

[canard.hw.logplayer module](#)

[canard.hw.loopback module](#)

[canard.hw.peak module](#)

[canard.hw.socketcan module](#)

#### 2.1.2 Module contents

### 2.2 canard.proto package

#### 2.2.1 Submodules

[canard.proto.isotp module](#)

[canard.proto.obdii module](#)

[canard.proto.uds module](#)

#### 2.2.2 Module contents

### 2.3 canard.test package

#### 2.3.1 Submodules

[canard.test.can\\_test module](#)

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Chapter 2. Subpackages

# CHAPTER 3

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Module contents

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